

What is claimed is :

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1 A filtering control method for improving the image quality of a bi-linear interpolated image in methods for getting a high resolution image from a low resolution image, comprising:

restoring a requested high resolution image  $f$  by finding an added filter coefficient  $Q$  of a  $PSF(P)$  and a bi-linear interpolation filter  $B$  from an equation  $f = Pg = PBz = Qz$ , herein the  $f$  is the high resolution image as requested,  $P$  is the PSF (Point Spread Function),  $g$  is the high resolution image found by the bi-linear interpolation method, and  $z$  is the low resolution image.

2. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 1; wherein the high resolution image  $f$  can be restored by performing an added function  $M(f)$  definition process for finding the  $PSF(H)$  from an equation  $g = Bz = Hf + n$ , herein the  $B$ ,  $H$  are bi-linear interpolation filters, and the  $n$  is a noise component generated by the assumed  $H$ .

3. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 1, wherein the high resolution image  $f$  is restored by finding a  $PSF(P)$  of a  $f = Pg$  function after finding the  $PSF(H)$  from the added function  $M(f)$ .

4. The filtering control method for improving the image quality of the

bi-linear interpolated image according to claim 2, wherein the added function  $M(f)$  is defined as  $M(f) = \|g - Hf\|^2 + \alpha \|Cf\|^2$ , herein the  $\alpha$  is a regularization parameter,  $C$  is a two-dimensional high frequency filter for finding mitigation of the original image.

5                    5.        The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 3, wherein the PSF(H) is found by using an equation  $H(k,l) = \frac{G(k,l)}{F(k,l)}$ , herein the  $G(k,l)$  is the component in the  $k,l$  frequency region of the bi-linear interpolated image, and the  $F(k,l)$  is the component in the  $k,l$  frequency region of the high resolution image.

10                   6.        The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 1, wherein the PSF(P) can be found by getting an IFT (Inverse Fourier Transform) by an equation

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$$P(k,l) = \frac{H^*(k,l)}{H^*(k,l)H(k,l) + C^*(k,l)C(k,l)}$$

                    7.        The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 4, wherein the regularization parameter  $\alpha$  is fixed as '1' in order to reduce a computational complexity.

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9. The filtering control method for improving image quality of the bi-linear interpolated image according to claim 4, wherein a two-dimensional gaussian filter is used as the two-dimensional high frequency filter C in order to  
5 determine the mitigation of the original image.

10. A filtering control method for improving image quality of a bi-linear interpolated image in methods for getting a high resolution image from a low resolution image, comprising :

10 defining an added function  $M(f)$  for finding a  $PSF(H)$  from an equation  $g=Bz=Hf+n$  ( $B$ ,  $H$  are bi-linear filters,  $N$  is a noise component generated by an assumed  $H$  when the  $H$  is a  $PSF$  (Point Spread Function),  $F$  is a requested high resolution image,  $z$  is a low resolution image, and  $g$  is a high resolution image gotten by the bi-linear interpolation method ;

15 finding a  $PSF(P)$  of a  $f=Pg$  function after finding the  $PSF(H)$  from the defined added function  $M(f)$  ; and

restoring the requested high resolution image  $f$  by finding an added filter coefficient  $Q$  of the  $PSF(P)$  and interpolation filter  $B$  from the equation  $f=Pg=PBz=Qz$ .

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25 11. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 10, wherein the added function  $M(f)$  is defined as  $M(f)=\|g-Hf\|^2+\alpha\|Cf\|^2$ , herein the  $\alpha$  is a regularization parameter, and  $C$  is a two-dimensional high frequency filter for finding the mitigation of the original image.

12. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 10, the PSF(H) is found by an equation  $H(k,l) = \frac{G(k,l)}{F(k,l)}$ , herein the  $G(k,l)$  is the component in the  $k,l$  frequency region of the bi-linear interpolated image, and the  $F(k,l)$  is the component in the  $k,l$  frequency region of the high resolution image.

13. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 10, wherein the PSF(P) is found by using an IFT (Inverse Fourier Transform) from an equation

$$P(k,l) = \frac{H^*(k,l)}{H^*(k,l)H(k,l) + C^*(k,l)C(k,l)}$$

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14. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 11, wherein the regularization parameter  $\alpha$  is fixed as '1' in order to reduce a computational complexity.

15. The filtering control method for improving the image quality of the bi-linear interpolated image according to claim 10 ~~or claim 13~~, the number of a kernel of the PSF(P) is differently set in accordance with an up-sampling value of the image.

16. The filtering control method for improving image quality of the bi-linear interpolated image according to claim 11, wherein a two-dimensional

gaussian filter is used as the two-dimensional high frequency filter C in order to determine the mitigation of the original image.

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